# 3d Brain Atlas Reconstructor Installation (Ubuntu)

**Note**: This procedure is valid for *Ubuntu 9.04* and *Ubuntu 10.04 LTS* and was tested on 4.08.2011. For guides related to *Ubuntu 8.04* see barSoftwareInstallation8.04?. Installation on other Ubuntu versions or other Linux distributions is similar.

- 1. Installing required packages
- 2. Getting the code

# Installing required packages

#### **Installation in Ubuntu 9.10**

1. Install the Visualization Toolkit and other graphics libraries:

```
sudo apt-get install \
libvtk5.2 libvtk5-dev libvtk5.2-qt4 libvtk5-qt4-dev \
tk8.5 tk8.5-dev \
python-vtk libgtkgl2.0-1 libgtkgl2.0-dev libgtkglext1 librsvg2-2 python-nifti
```

2. Install python related packages:

```
sudo apt-get install \
python-gtkglext1 python-rsvg python-opengl python-numpy python-scipy python-wxgtk2.6
```

3. Other packages:

```
sudo apt-get install \ potrace pstoedit python-setuptools subversion python-epydoc
```

If you are a developer you may also want to install optional packages with documentation:

```
sudo apt-get install vtkdata vtk-doc vtk-examples
```

### **Installation in Ubuntu 10.04**

Install the following packages:

```
sudo apt-get install \
libvtk5.2 libvtk5-dev libvtk5.2-qt4 libvtk5-qt4-dev \
tk8.5 tk8.5-dev \
python-vtk libgtkgl2.0-1 libgtkgl2.0-dev libgtkglext1 librsvg2-2 python-nifti

sudo apt-get install \
python-gtkglext1 python-rsvg python-opengl python-numpy python-scipy python-wxgtk2.6

sudo apt-get install \
potrace pstoedit python-setuptools subversion python-epydoc
```

#### **Installation in Ubuntu 10.10**

### Install the following packages:

```
sudo apt-get install \
libvtk5.4 libvtk5-dev libvtk5.4-qt4 libvtk5-qt4-dev \
tk8.5 tk8.5-dev \
python-vtk libgtkgl2.0-1 libgtkgl2.0-dev libgtkglext1 librsvg2-2 python-nifti

sudo apt-get install \
python-gtkglext1 python-rsvg python-opengl python-numpy python-scipy python-wxgtk2.8

sudo apt-get install \
potrace pstoedit python-setuptools subversion python-epydoc
```

Once all the packages are installed it is time to create the directory structure.

# Getting the code

It is assumed that the main directory dedicated for 3dBAR is /home/\$USERNAME/3dbar. if you want to install it in another directory, replace 3dbar with the desired path.

To get the latest stable version of 3dBAR fill out <u>the following form</u> then download 3dBAR using the link provided via email.

Unzip the file to your home directory and go to the 3dBAR directory:

```
mkdir ~/3dbar; unzip 3dbar_latest.zip -d ~/3dbar; cd ~/3dbar/3dbar_publ;
```

Created directories have the following purposes:

- bin: Holds all executable files, atlas parsers and auxiliary scripts
- **lib**: Holds the 3dBAR api
- atlases: Directory, where the source data, *CAF datasets* and reconstructed models are stored. Each dataset (denoted as DATASET\_NAME) contains the following subdirectories:
  - ♦ atlases/DATASET\_NAME/src : Here the source data is located. It can be placed manually by a user or downloaded from internet depending on a particular parser.
  - ♦ atlases/DATASET\_NAME/caf : This is the directory where a CAF dataset is generated by specific parsers.
  - atlases/DATASET NAME/reconstructions: The directory for reconstructed models.